

Statistics and geometry of passive scalars in turbulence

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(Received 17 May 2005; accepted 18 October 2005; published online 16 December 2005)

We present direct numerical simulations of the mixing of the passive scalar at modest Taylor microscale ($10 \leq R_\lambda \leq 42$) and Schmidt numbers larger than unity ($2 \leq Sc \leq 32$). The simulations resolve below the Batchelor scale up to a factor of 4. The advecting turbulence is homogeneous and isotropic, and is maintained stationary by stochastic forcing at low wave numbers. The passive scalar is rendered stationary by a mean scalar gradient in one direction. The relation between geometrical and statistical properties of scalar field and its gradients is examined. The Reynolds numbers and Schmidt numbers are not large enough for either the Kolmogorov scaling or the Batchelor scaling to develop and, not surprisingly, we find no fractal scaling of scalar level sets, or isosurfaces, in the intermediate viscous range. The area-to-volume ratio of isosurfaces reflects the nearly Gaussian statistics of the scalar fluctuations. The scalar flux across the isosurfaces, which is determined by the conditional probability density function (PDF) of the scalar gradient magnitude, has a stretched exponential distribution towards the tails. The PDF of the scalar dissipation departs distinctly, for both small and large amplitudes, from the log-normal distribution for all cases considered. The joint statistics of the scalar and its dissipation rate, and the mean conditional moment of the scalar dissipation, are studied as well. We examine the effects of coarse-graining on the probability density to simulate the effects of poor probe-resolution in measurements. © 2005 American Institute of Physics. [DOI: 10.1063/1.2140024]

I. INTRODUCTION

The mixing of passive scalars in the presence of turbulent motion is a subject of great theoretical and practical interest. Examples of its ubiquitous applications arise in reacting flows and combustion, mixing of salt and plankton in oceans and of pollutants in the atmosphere, as well as mixing of biological substances. Much experimental effort has thus been invested on mapping scalar fields in three dimensions, usually by reconstructing them from several planar cuts taken in quick succession in time (see Refs. 1–6 for work on turbulent liquid or air jets and Refs. 7 and 8 for work on diffusion flames). The Schmidt number $Sc = \nu / \kappa$, where ν is the kinematic viscosity of the advecting fluid and κ is the scalar diffusivity, plays an important role in determining the nature of mixing. For the following, our focus will be on Schmidt numbers larger than unity.

The finest scales of the scalar are generally thought to be of the order of the Batchelor scale, defined as $\eta_B = \eta / \sqrt{Sc}$, where η is the Kolmogorov scale given by $\eta = \nu^{3/4} / \langle \epsilon \rangle^{1/4}$, where ϵ is the local energy dissipation rate of turbulence, and the angular brackets indicate a suitable average. For a given flow, the Batchelor scale becomes smaller for larger Sc . Thus, the required resolution for large Sc , common in liquid flows, is hard to attain experimentally.¹⁰

With modern computers, it is possible to resolve scalar mixing in turbulence at high Schmidt numbers.^{11–15} Schumacher *et al.*¹⁶ showed that it is sometimes necessary to resolve scales that are finer than η_B . Such fine resolutions are desired, for instance, for obtaining reliable results on the ex-

treme fluctuations (both small and large) of scalar gradients and scalar dissipation rate. We resolve scales finer than the Batchelor scale by a factor of 4. This fine resolution limits the ranges of Sc and R_λ examined, where R_λ is the Taylor microscale Reynolds number. Nevertheless, we can study trends with Sc and R_λ in limited ranges of these parameters, with a full three-dimensional field resolved extremely well. In particular, we consider relations between geometric and statistical properties of passive scalars and their spatial variations with respect to Sc for a given turbulent flow, as well as those with the Reynolds number for a given Sc .

The paper is organized as follows. Section II briefly reports the numerical details and parameters. We consider the box-counting properties and area-to-volume ratio of the passive scalar isosurfaces in Sec. III, while Sec. IV considers the properties of the instantaneous scalar flux across isosurfaces. Section V presents an analysis of the statistics of scalar dissipation including conditional statistics. Conclusions and summary are presented in the final section.

II. NUMERICAL SIMULATIONS

We solve simultaneously the Navier-Stokes equations for an incompressible flow $\mathbf{u}(\mathbf{x}, t)$ and the advection-diffusion equation for the passive scalar field $\theta(\mathbf{x}, t)$ in box-type three-dimensional turbulence with the classical pseudospectral method that uses fast Fourier transformations and a 2/3 dealiasing. The boundary conditions for the velocity and scalar field are both periodic. The simulation domain has a length

TABLE I. List of parameters for the present DNS runs. N is the number of grid points on each side of the computational cube, ν is the kinematic viscosity, $\langle \epsilon \rangle$ is the mean energy dissipation rate, $u_{\text{rms}} \equiv \langle u_x^2 \rangle^{1/2}$ is the rms velocity fluctuation in the x direction, $k_m = \sqrt{2N}/3$ is the maximum wave number allowed in the simulations, $R_\lambda = \sqrt{15/(\nu \langle \epsilon \rangle)} \langle u_x^2 \rangle$ is the Taylor micro-scale Reynolds number, and L is the integral scale of turbulence. Its magnitude is to be compared with the linear dimension of the box, which is 2π in all cases. T_{av} is the statistical averaging time, to be compared here with the large-eddy turnover time defined as $T_E = \langle \mathbf{u}^2 \rangle / 2\langle \epsilon \rangle$; Sc is the Schmidt number, $\theta_{\text{rms}} \equiv \langle \theta^2 \rangle^{1/2}$ is the rms passive scalar fluctuation, $\langle \epsilon_\theta \rangle$ is the mean scalar dissipation rate, and L_θ is the integral scale of the passive scalar. Both integral scales are calculated as in Ref. 44.

	Run number							
	1		2		3			
N	512		1024		1024			
ν	0.0333		0.0133		0.005			
$\langle \epsilon \rangle$	0.1		0.1		0.1			
u_{rms}	0.394		0.483		0.486			
$k_m \eta$	33.56		33.56		15.93			
R_λ	10		24		42			
L	1.018		0.920		0.758			
T_{av}/T_E	9.1		1.2		1.1			
Sc	2	8	32	2	8	32	32	
θ_{rms}	1.390	2.012	2.572	1.269	1.604	1.917	1.548	
$\langle \epsilon_\theta \rangle$	0.330	0.391	0.420	0.307	0.345	0.372	0.306	
$k_m \eta_B$	23.68	11.84	5.92	23.68	11.84	5.92	2.82	
L_θ	0.707	0.587	0.477	0.562	0.447	0.357	0.289	

of 2π in each coordinate direction and is resolved by an equidistant grid with N^3 points. The equations are

$$\frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{u} = -\nabla p + \nu \nabla^2 \mathbf{u} + \mathbf{f}, \quad (1)$$

$$\nabla \cdot \mathbf{u} = 0, \quad (2)$$

$$\frac{\partial \theta}{\partial t} + (\mathbf{u} \cdot \nabla) \theta = \kappa \nabla^2 \theta - u_y G. \quad (3)$$

Here, $p(\mathbf{x}, t)$ is the kinematic pressure field. The turbulence is sustained by a random force density $\mathbf{f}(\mathbf{x}, t)$ (see Schumacher¹⁷ for details) and the scalar gradient is constant in the y direction, i.e., $\mathbf{G} = (0, G, 0)$ with $G=1$; u_y is the turbulent velocity component in the direction y . The equations are integrated in time by a second-order predictor-corrector scheme. Parameters of the simulations and some statistical results are listed in Table I. The spectral resolution exceeds the usual criterion of $k_{\text{max}} \eta_B \geq 1.5$ by a factor of about 4. A detailed comparison between these high-resolution data and those with the nominal resolution employed in most direct numerical simulation (DNS) studies was presented in Schumacher *et al.*¹⁶ Their conclusion was that superfine resolution would be needed to capture specific features of the scalar dissipation rate

$$\epsilon_\theta(\mathbf{x}, t) = \kappa [\nabla \theta(\mathbf{x}, t)]^2, \quad (4)$$

such as the sheet-like structures in which the extreme events are found. We shall exploit the present fine resolution for just such purposes.

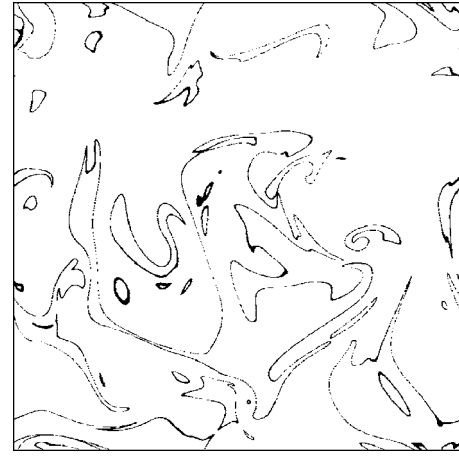


FIG. 1. Two-dimensional instantaneous slice through the fluctuating passive scalar field $\theta(\mathbf{x}, t)$ for the level of $0.8\theta_{\text{rms}}$ (i.e., $X=0.8$). The side length of the box (run 2) is about 90η and resolved with $N=1024$ in each coordinate direction. $R_\lambda=24$, $\text{Sc}=32$.

III. SCALAR ISOSURFACES

A. Box-counting dimension

It is well known that, for Schmidt numbers exceeding unity, the passive scalar is filamented in structure and mixed by smooth flow in a continual stretch-twist-fold scenario.¹⁸ An open point is whether the scalar contours accompanying such dynamics, when diffusion and external driving are included, generate fractal sets. Neither the inertial-convective range nor the viscous-convective Batchelor range obtains for the present moderate values of R_λ and Sc, so it would be surprising if the fractal scaling is found. Nevertheless, the issue is worth a brief examination as a prelude to the study of area-to-volume ratio of scalar interfaces that follows in Sec. III B. If the surface is indeed a fractal, it is easy to write down the surface area in terms of its dimension and the cut-off scales terminating the scaling behavior.¹⁹

Let us define the scalar level sets as

$$L_X = \{\mathbf{x}: X - \delta X \leq \theta(\mathbf{x}, t) / \theta_{\text{rms}} \leq X + \delta X\}, \quad (5)$$

where X is the ratio of the chosen amplitude threshold to the rms value of the scalar, θ_{rms} . Operationally, δX is taken to be 2.5% of θ_{rms} for each (R_λ, Sc) . Figure 1 shows a level set of the scalar field around a value of $0.8\theta_{\text{rms}}$ for $\text{Sc}=32$ and $R_\lambda=24$. Similar pictures with different thresholds show that levels of high intensity are embedded within isolevels of lower intensity. The isolevels become increasingly disconnected with increasing intensity and become isolated islands embedded within an isocontour of lower magnitude. This observation is consistent with mixing studies in a jet by Villermaux and Innocenti.⁴ In the box-counting procedure described, for example, in Falconer,²⁰ one counts the number of cubes N_δ of side length δ that cover the level set L_X completely. This procedure is repeated for various values of δ . The box-counting dimension D of a (fractal) level set is defined then as

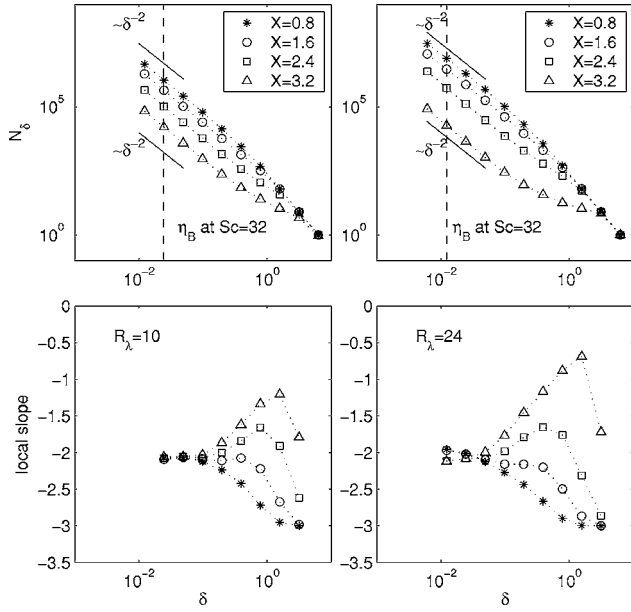


FIG. 2. Three-dimensional box-counting data for scalar level sets L_X as defined in (5) for $Sc=32$ and for $R_\lambda=10$ (left column) and $R_\lambda=24$ (right column). The values of X are 0.8 (asterisks); 1.6 (circles); 2.4 (squares); and 3.2 (triangles). The vertical dashed lines in the upper panels show the corresponding values of η_B . Short solid lines mark the algebraic slope with δ^{-2} in the log-log plot. All the isosurfaces have a region with a common exponent of 2 at the smallest scales. The lower panels show the local slope $d \log(N_\delta)/d \log(\delta)$ as a function of δ . Symbols are as in the upper figures.

$$D = - \lim_{\delta \rightarrow 0} \frac{\log N_\delta}{\log \delta}. \quad (6)$$

In practice, it is clear that one cannot apply the limit $\delta \rightarrow 0$, and one seeks an algebraic scaling, $N_\delta \sim \delta^{-D}$, in a finite range.

The upper two panels of Fig. 2 show the log-log plots resulting from box-counting for data sets of runs 1 and 2 at $Sc=32$. A constant slope with exponent D would give the box-counting dimension of the scalar level set. However, the local slope given by

$$D(\delta) = - \frac{d \log N_\delta}{d \log \delta} \quad (7)$$

varies continuously, as shown in the lower panels of Fig. 2. Although our simulations cover three orders of magnitude of scales, it is clear that no power-law scaling exists for reasons mentioned at the beginning of this section. The smallest few values of δ give a local slope of 2, for all X , which means that the level sets at those scales become smooth sheets. We interpret (the slightly) smaller slopes for intermediate scales of δ as arising from the disconnected shape of the isosurface. Indeed, this patchiness increases with the level X , thus giving a smaller magnitude of the local slope.

The conclusion from this study is that fractal behavior of the isosurface is not obtained in the range of R_λ and Sc considered here. We want to emphasize, however, that this finding has no bearing on the past experimental work as reported in Refs. 3, 4, 19, and 21. The differences such as may exist in these experimental studies require a separate discussion which lies outside the scope of this paper. We

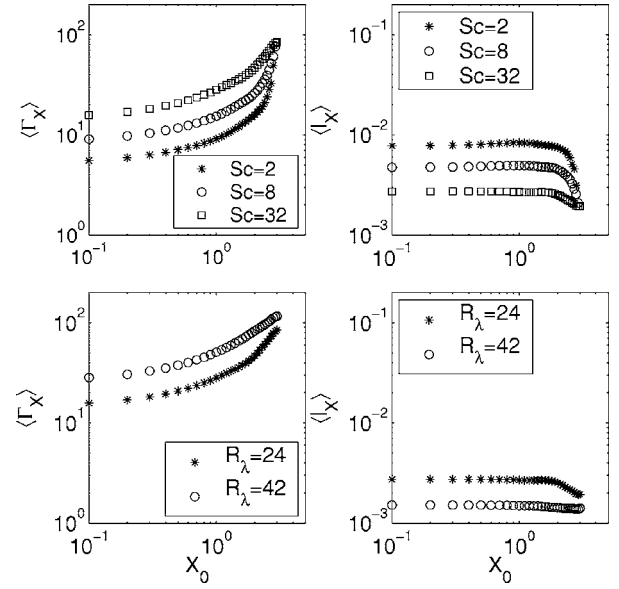


FIG. 3. Left column: mean of the area-to-volume ratio $\langle \Gamma_X \rangle$ as a function of the isosurface X_0 in a log-log plot. Upper panel shows data for run 2 at three different Schmidt numbers. Lower panel shows the quantity at $Sc=32$ for runs 2 and 3. Right column: the corresponding transition scale $\langle \ell_X \rangle$ as derived from Eq. (10).

expect that the fractal property in the inertial-convective range requires high Reynolds numbers while that in the viscous-convective range requires high values of Schmidt and Reynolds numbers.

B. Area-to-volume ratio

Since we do not have fractal scaling for the ranges of parameters considered here, it is necessary to compute the area of isosurfaces directly. In reacting flows, a quantity of some importance is the ratio of the isosurface area content to the volume which encloses it.²² This ratio is numerically calculated as follows. We first define the set

$$\tilde{L}_X = \{\mathbf{x}: \theta(\mathbf{x}, t)/\theta_{\text{rms}} \geq X_0\}. \quad (8)$$

The set is computed for each snapshot separately and the results are averaged with respect to time subsequently. We mark all grid points that belong to \tilde{L}_X by an indicator function $I_{ijk} \equiv 1$. For all other points, $I_{ijk} \equiv 0$. Here i, j , and k denote the indices of the grid vertices running from 1 to N . All boundary points of the set \tilde{L}_X have a number of nearest neighbors, N_{ijk} , which ranges from 1 to 5; the inner points of \tilde{L}_X have 6 nearest neighbors. The number of inner points is denoted by \bar{N}_{ijk} . The area-to-volume ratio Γ_X of the set \tilde{L}_X is given by

$$\Gamma_X = \frac{A_X}{V_X} = \frac{1}{\bar{N}_{i,j,k} \Delta x} \sum_{(i,j,k) \in \tilde{L}_X} (6 - N_{ijk}), \quad (9)$$

with grid spacing Δx , with $\bar{N}_{i,j,k} \neq 0$. The left column of Fig. 3 shows the average of the area-to-volume ratio, with $\langle \Gamma_X \rangle$ taken over several snapshots. Three trends are clear: first, the ratio grows with increasing X_0 , which indicates a higher degree of disconnection of the isosurfaces. Second, the ratio is

larger for larger Schmidt numbers. This is because mixing then occurs over ever finer scales whose contours are stretched and folded by the flow. Finally, a larger Reynolds number enables the scalar to be stirred more efficiently on all scales, yielding larger area-to-volume ratios with increasing Reynolds number.

We relate this geometric measure to statistical properties of the passive scalar fluctuations following ideas that were used in the slightly different context of interfacial dynamics for a turbulent jet.²³ As is shown later (see Sec. V B), the scalar fluctuations are close to the Gaussian probability density function, $p(X) = 1/\sqrt{2\pi} \exp(-X^2/2)$, with a slight sub-Gaussian behavior in the far tails. The average of the ratio $\langle \Gamma_X \rangle$ should therefore be related to $p(X)$. For $X = X_0$, we set

$$\begin{aligned} \langle \Gamma_{X_0} \rangle \langle \ell_{X_0} \rangle &\approx \frac{\exp(-X_0^2/2) dX_0}{\int_{X_0}^{\infty} \exp(-y^2/2) dy} \\ &= \frac{\exp(-X_0^2/2) dX_0}{\sqrt{\pi/2} [1 - \text{erf}(X_0/\sqrt{2})]}, \end{aligned} \quad (10)$$

where $\text{erf}(x) = (2/\sqrt{\pi}) \int_0^x \exp(-y^2) dy$ is the error function. For the following, we discuss results for $X_0 > 0$, but everything holds for $X_0 < 0$ just the same way. The additional scale $\langle \ell_{X_0} \rangle$ on the left-hand side of Eq. (10) has to appear for dimensional reasons since the right-hand side is dimensionless.

The scale $\langle \ell_{X_0} \rangle$ is related to the surface-to-volume ratio Γ , and is small when that ratio is large. Since Γ becomes larger for “rougher” surfaces, the scale is a characteristic measure of the transition between smooth and rough isosurfaces, perhaps describing the average connectedness and regularity of the isosurface. We may thus call it the transition scale. It is a global average measure just as Γ . Its trends with Sc and R_λ are shown in the right column of Fig. 3. The straight horizontal parts of $\langle \ell_X \rangle$ for $X \leq 2$ at fixed Sc and R_λ are the “geometric fingerprints” of the Gaussianity of the scalar fluctuations. Finally, we want to note that the relation (10) holds only for isosurfaces that are not fractal.

IV. FLUX ACROSS SCALAR ISOSURFACES

One reason for the interest in the area of an isosurface is the flux across it. For example, in non-premixed turbulent combustion the isosurface of the stoichiometric mixture fraction plays an important role and the variation of gradients across it are important for closure models.^{10,22,24} This can be calculated by integrating the flux across all infinitesimal elements of the surface. Since the flux is proportional to the product of the area and the gradient of the concentration across it, it is necessary to know the gradient across each infinitesimal element of the surface. The gradient can itself be a highly fluctuating variable.

The present data allow the computation of gradients and fluxes across infinitesimal elements of isosurfaces. The (differential) flux across an infinitesimal area element dA of an isosurface is given by

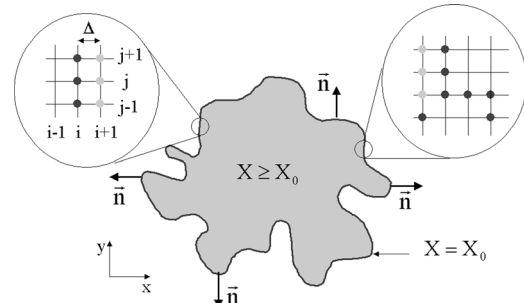


FIG. 4. Sketch of the scalar gradient flux calculation across a passive scalar isosurface $X = X_0$. The illustration is for a two-dimensional case (but the data presented in the next figure are for the surface in three dimensions). Black points lie on the boundary, whereas the gray points are the interior of \tilde{L}_X . The inner points are the volume that is used for Γ_X [see Eq. (9)].

$$d\Phi(X_0) = -\nabla X|_{X=X_0} \cdot \mathbf{n} dA, \quad (11)$$

where \mathbf{n} is the outward unit normal (see Fig. 4 for $X_0 > 0$).

The probability density function (PDF) of $d\Phi(X_0)$ is then fully determined by the PDF of scalar gradient magnitude at the isosurface $X = X_0$

$$p(d\Phi(X_0)) = p(-|\nabla X|_{X=X_0} dA). \quad (12)$$

Thus, the quantity of interest is a conditional PDF $p(|\nabla X|_{X=X_0})$ which is calculated as follows. First, as in the preceding section, we mark all the grid points for which $\theta(\mathbf{x}, t) \geq X_0 \theta_{\text{rms}}$ as *active* points; their grid sites are marked with $I_{i,j,k} \equiv 1$; for all other points, $I_{i,j,k} \equiv 0$. Gradients are calculated on $\partial \tilde{L}_X$ afterwards. Sparser grid resolutions would require a trilinear interpolation between the grid cells.²⁵

The result is plotted in Fig. 5. A stretched exponential behavior is observed for a large range of the PDF, with the tails decaying more rapidly for larger X . The PDFs suggest also that there is a considerable local variation of the flux across interfaces $X = X_0$. The fluctuations increase significantly with increase in Sc as well as R_λ . For both Reynolds numbers, one can see low-probability instances whose gradients are of the order of $\theta_{\text{rms}}/\eta_B$. This particular gradient value is indicated in the lower right figure by the two vertical arrows.

V. STATISTICS OF SCALAR DISSIPATION RATE

A. The PDF of the scalar dissipation rate

The scalar dissipation rate plays a central role in determining turbulent mixing. In combustion, for example, its properties enter fast chemistry models,²⁶ modeling of thin reactive layers called flamelets,²⁷ which are embedded and advected in the turbulent flow, and conditional-moment closures for the evolution of the mixture fraction in nonpremixed cases.²⁸

With $p(|\nabla \theta|) \sim \exp(-C|\nabla \theta|^\alpha)$ for large $|\nabla \theta|$, as was seen in the last section, we expect that the tails of the PDF of ϵ_θ will have stretched exponential behavior given by

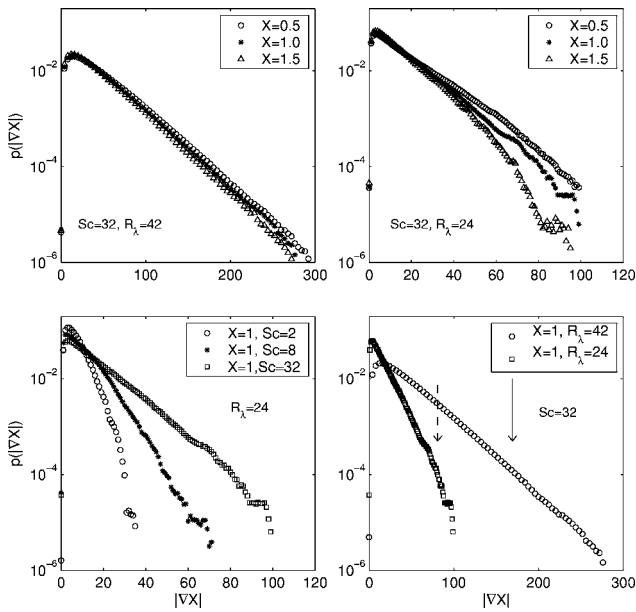


FIG. 5. The probability density function of the magnitude of scalar gradient, $|\nabla X|$, taken at isocontour levels $X=X_0$. Upper left: The data are for run 3, $Sc=32$, for three different levels: $X=0.5$ (open circle), $X=1.0$ (asterisk), and $X=1.5$ (triangle). Upper right: The data are for run 2, $Sc=32$, for three different levels: $X=0.5$ (open circle), $X=1.0$ (asterisk), and $X=1.5$ (triangle). Lower left: Schmidt number dependence of the flux. Data are for run 2 at $X=1$: $Sc=2$ (circle), $Sc=8$ (asterisk), and $Sc=32$ (square). Lower right: Reynolds number dependence of the flux for $Sc=32$ and for $X=1$, with $R_\lambda=24$, run 2 (square) and $R_\lambda=42$, run 3 (circle). The vertical arrows (dashed for run 2 and solid for run 3) indicate X/η_B with $X=1$.

$$p(\epsilon_\theta > \langle \epsilon_\theta \rangle) = \frac{C_1}{\sqrt{\epsilon_\theta}} \exp(-C_2 \epsilon_\theta^{\alpha/2}), \quad (13)$$

where C_1 and C_2 are constants. Such statistics were derived analytically for scalar advection in smooth and white-in-time flows for the limit $Pe \rightarrow \infty$ and $\alpha=2/3$ was found.^{29,30} In Fig. 6 we show the PDF of the scalar dissipation rate in a log-

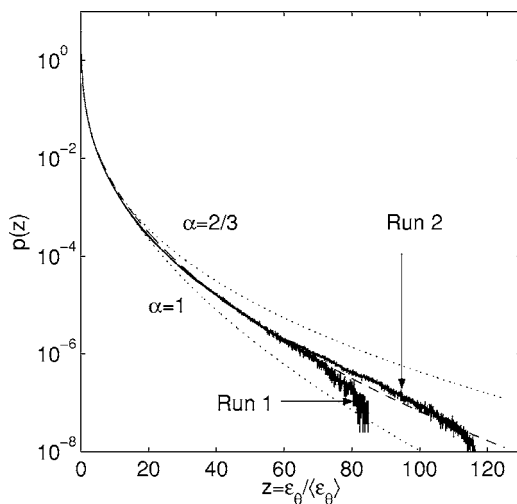


FIG. 6. Log-linear plot of the probability density function of the scalar dissipation rate, normalized to the mean value. Data are for run 1 and run 2 at $Sc=32$. Fits to the data for $z \geq 10$ with the stretched exponential term of (13) are also plotted, and the corresponding exponents α are shown. The dashed line is the optimum of a least-squares fit resulting in $\alpha=0.86$.

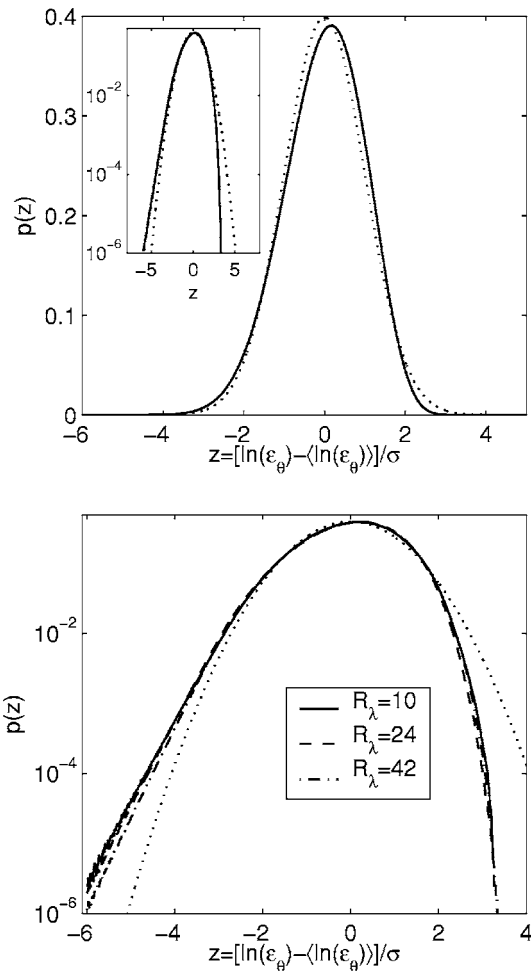


FIG. 7. Upper panel: Probability density function of $z=[\log(\epsilon_\theta) - \langle \log(\epsilon_\theta) \rangle] / \sigma$ with $\sigma = \sqrt{\langle [\log(\epsilon_\theta)]^2 \rangle - \langle \log(\epsilon_\theta) \rangle^2}$. Data for run 2, with $Sc=32$, are compared with the corresponding log-normal distribution having the same mean and standard deviation. Data in each panel are plotted as a solid line and the log-normal distribution as a dotted line. The inset shows the same data in a log-linear plot that highlights the tails. Deviations from log-normality are quite visible. Lower panel: Log-linear plots of the same type of data for three different Reynolds numbers and $Sc=32$.

linear plot for runs 1 and 2; $Sc=32$. In addition, we fit the exponential part of the formula (13) to the data for the range of $\epsilon_\theta > 10\langle \epsilon_\theta \rangle$. The cases $\alpha=1$ (pure exponential gradient) and $\alpha=2/3$ (corresponding to the theory in Refs. 29 and 30) bound both sets of data from below and above, respectively, with the optimal least-squares fit (dashed) corresponding to $\alpha=0.86$.

This form of the PDF departs clearly from log-normality. Figure 7 (upper panel) shows the PDF of ϵ_θ for run 2 (see Table I). The linear scale reveals that the log-normal approximation is not particularly good near the core. The logarithmic scale (inset) shows that the tails depart from log-normality as well: low dissipation values show a fatter tail and high dissipation values fall short of the log-normal. These departures from log-normality are robust for all Reynolds and Schmidt numbers considered here; this is demonstrated in the lower panel of Fig. 7, where we plot the data for $Sc=32$ at the three Reynolds numbers $R_\lambda=10, 24$, and 42 .

There has been much discussion in the literature about

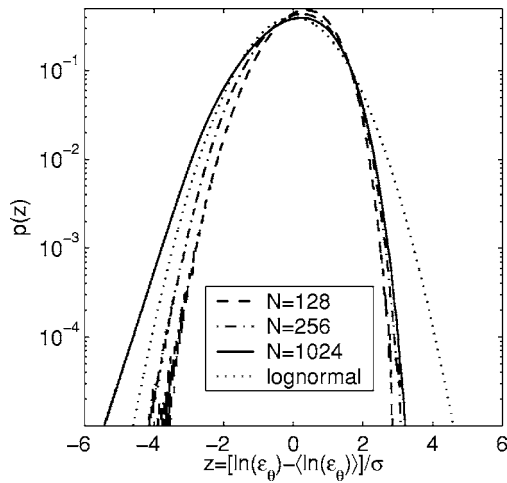


FIG. 8. Log-linear plot of the PDF of the scalar dissipation rate at $Sc=32$ for run 2. As in Fig. 7, solid line are the original data at a resolution of $N=1024$ and the dotted line is for the corresponding log-normal distribution. The analysis was repeated for the coarse-grained scalar dissipation field, and the dashed line shows the result of coarse-graining over 8^3 cubes, giving an effective resolution of $N=128$; the dashed-dotted curve is for 4^3 cubes with an effective resolution of $N=256$.

the log-normality or otherwise of scalar dissipation, and we might cite an early paper Sreenivasan *et al.*³¹ and a recent one by Su and Clemens⁶ to illustrate experimental results and the discussions accompanying them. Often, measured deviations from log-normality are attributed to poor measurement resolution or to low Reynolds numbers or to noise in the experimental system.

In order to shed some light on how the PDFs depend on probe resolution in an experiment, we plot in Fig. 8 the PDFs that result when the statistics are taken over successively coarse-grained scalar dissipation fields. The coarse-graining scale does not produce a qualitatively different result on the right side of the distribution ($z > 0$), for which the PDF remains sub-Gaussian for all cases. For negative z , there is probably a particular coarse-graining that may collapse the data on to the log-normal curve, but this coincidence would be accidental at best. On the effect of Reynolds number, we can only comment that the behavior is similar for both Reynolds numbers considered here. The double-precision calculations throughout this work keep the noise effects under control. We thus conclude that, while the PDF is roughly log-normal, the deviations from it are considerable.

B. The joint statistics of scalar and scalar dissipation

In Fig. 9 we show the joint PDF $p(\theta, \epsilon_\theta)$, where $p(\theta, \epsilon_\theta)d\theta d\epsilon_\theta$ is the probability of having the scalar dissipation rate between ϵ_θ and $\epsilon_\theta + d\epsilon_\theta$ and the scalar fluctuation between θ and $\theta + d\theta$. The figure shows the joint PDF for two Reynolds numbers and $Sc=32$. The upper row of Fig. 9 shows isocontours of $p(\theta, \epsilon_\theta)$ which are equidistant in units of the logarithm to base 10. The joint PDF is wider with respect to the θ axis for the case of larger Reynolds number. This is due to the fact that the scalar field and the dissipation field acquire larger amplitudes with increasing R_λ . The lower panels show the scalar PDF calculated by integrating $p(\theta, \epsilon_\theta)$

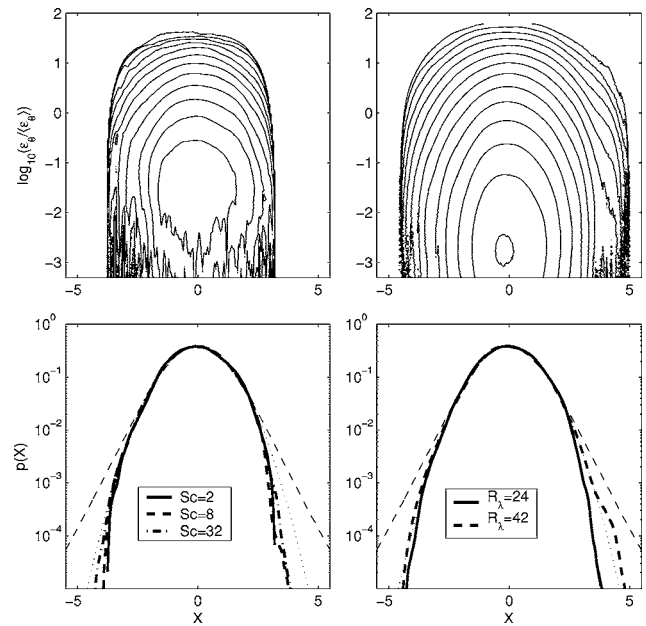


FIG. 9. Upper row: Joint probability density function $p(\theta/\theta_{rms}, \epsilon_\theta/\langle\epsilon_\theta\rangle)$ for the runs at $R_\lambda=24$ (left) and $R_\lambda=42$ (right), both for $Sc=32$. The isocontour levels are equidistant in units of the logarithm to base 10, varying from -6 to 0.5 in steps of 0.5 . The joint densities for large negative values of $\log(\epsilon_\theta)$ (i.e., scalar dissipation rates smaller than $10^{-3}\langle\epsilon_\theta\rangle$) are truncated for reasons of poor convergence. Lower row: scalar PDF for $R_\lambda=24$ and Sc values indicated in the legend (left). The thin dashed line is a theoretical prediction for the scalar PDF, $p(X)=C/(1+kX^2)^{1+1/2k}$, for advection in a random flow with fit parameters $C=0.4$, $k=0.08$, X being θ/θ_{rms} (Ref. 32). The thin dotted line is a Gaussian distribution. Scalar PDF at $Sc=32$ for two different Reynolds numbers as indicated in the legend are shown in the right panel. Both thin lines are as in the lower left panel.

over ϵ_θ . We observe an almost Gaussian shape of $p(\theta)$ for both Reynolds numbers (as anticipated in Sec. III B). Additionally, we have compared our results with the limiting shape for a scalar field PDF that was analytically predicted for advection in a random flow.³² The comparison is good only for small amplitudes of θ .

A nearly Gaussian PDF for the scalar fluctuations is in agreement with a number of other studies at $Sc \lesssim 1$, such as heated grid turbulence,³³ isotropic turbulence with a mean scalar gradient,^{34,35} a homogeneous shear flow with heating by a constant mean temperature gradient.³⁶ In our simulations, the fluctuations extend to approximately $\pm 4.5\theta_{rms}$ and the deviations in the tails are slightly sub-Gaussian. Exponential tails of the PDF, as found by Jayesh and Warhaft,³⁷ were not observed for our range of parameters. It should be mentioned that they were also predicted analytically for a white-in-time smooth Gaussian flow by Shraiman and Siggia.³⁸ Furthermore, exponential tails have been suggested to result from an aggregation process of elementary local straining motion events, and close-to-exponential tails have been observed in jets sufficiently far away from the nozzle exit.³⁹

Overholt and Pope³⁴ argued that the nearly Gaussian or slightly sub-Gaussian statistics may result from the limited size of the simulation box in relation to the integral scale. The ratio of our box size to the integral scale of the flow, $2\pi/L$, is about 6 to 8 (see Table I); in terms of the integral

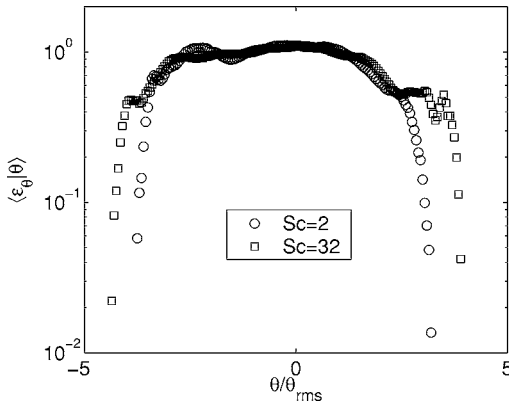


FIG. 10. Mean conditional moment of the scalar dissipation rate for Schmidt numbers $Sc=2$ and 32 . Data are for run 2 in Table I.

scale of the passive scalar at the largest Schmidt number, the ratio $2\pi/L_\theta$ varies from 13 to 21. This is significantly larger than the corresponding scale ratios in the experiment of Jayesh and Warhaft. The available evidence thus suggests that the relative size of the box size to the integral scale is not responsible for the shape of the PDF. A plausible argument can be made that the ratio L/L_θ might be a more appropriate quantity. We have attempted to vary this ratio in the simulations, but the results are still not conclusive.

The average of the scalar dissipation rate conditioned on the relation $\theta(\mathbf{x}, t) = \psi$ is denoted by $\langle \epsilon_\theta | \theta = \psi \rangle$. The conditional average is defined by means of the conditional probability density function $p(\epsilon_\theta | \theta)$, as

$$\langle \epsilon_\theta | \theta = \psi \rangle = \int_0^\infty d\epsilon_\theta \epsilon_\theta p(\epsilon_\theta | \theta = \psi). \quad (14)$$

The conditional probability density function can be expressed via the joint probability density function of having the scalar dissipation between ϵ_θ and $\epsilon_\theta + d\epsilon_\theta$ and the scalar between θ and $\theta + d\theta$, so that

$$p(\epsilon_\theta | \theta = \psi) = \frac{p(\theta = \psi, \epsilon_\theta)}{p(\theta = \psi)}. \quad (15)$$

Figure 10 shows the conditional moments for $Sc=2$ and 32 . It is well known that the conditional moment is constant⁴⁰ if the scalar distribution is strictly Gaussian. As can be seen in Fig. 10, our numerical results confirm this prediction for scalar fluctuation levels of less than about three standard deviations. For larger scalar fluctuation levels, there is a considerable drop in ϵ_θ for large values of θ , in contrast, say, to the behavior of the energy dissipation field ϵ with respect to the velocity fluctuations.⁴¹

Experiments in inhomogeneous flows⁴² show that the constancy of the conditional moment holds roughly on the centerline of turbulent jets and wakes. The behavior off-center is quite complex, and the boundary layer flows are intrinsically different.

VI. SUMMARY AND CONCLUSIONS

We have studied numerically the dynamics of passive scalars advected in homogeneous isotropic turbulence for three Schmidt numbers $Sc > 1$ and three Reynolds numbers, R_λ . These Reynolds and Schmidt numbers are moderate but comparable to those of many laboratory experiments on reacting flows. Usually, in such flows, neither the inertial range nor the viscous-convective range is well developed. The most important range of scales then belong to the so-called intermediate viscous range, which essentially pertain to the crossover between the inertial and viscous ranges of scales.^{16,43} In this range, rough velocity filaments reach down into the viscous range below the Kolmogorov scale η and stir the scalar. As reported in Ref. 16, the intermediate viscous range becomes more extended with increasing Reynolds number. We have paid particular attention to the grid resolution of the simulations, which exceeds the nominal value by a factor of four, to ensure that the high intensity events of the scalars and their gradient fields are resolved well.

The first quantity considered is the area-to-volume ratio of isoscalar surfaces because of its fundamental relevance to reacting flows. For the Reynolds and Schmidt numbers considered here, the fractal scaling of isoscalar level sets is not obtained and thus cannot be used to estimate the area-to-volume ratio. This ratio, computed here directly, increases with an increase in the passive scalar isoscalar level, the Schmidt number, and the Reynolds number. In detail, these increasing trends depend on the statistics of the scalar itself, which is found here to be nearly Gaussian.

We have defined a so-called transition scale $\langle \ell_X \rangle$ that becomes smaller with increasing surface-to-volume ratio of the isosurface corresponding to the scalar magnitude X (normalized by the rms value). Quite understandably, the isosurface becomes “rougher” and more disconnected with increasing Sc and increasing Reynolds number, but is not dependent on X itself—except when X is large. The flat behavior of the scale $\langle \ell_X \rangle$ for $X \lesssim 2$ can be considered a geometric confirmation of the nearly Gaussian probability density function $p(X)$ of the scalar. For large X , there is a tendency for $\langle \ell_X \rangle$ to decrease with X , this being attributable to the sub-Gaussian behavior of $p(X)$ in the tail region. The flux across the interface is a strongly fluctuating quantity from one differential area element to another, and its distribution is closely exponential. The fluctuations increase rapidly with increase in Sc as well as R_λ . However, with low probability, gradients of the order of magnitude θ_{rms}/η_B do occur in the scalar field. This clearly suggests the existence of sharp fronts accompanied by large jumps in the scalar concentration.

The scalar dissipation rate departs from log-normality more than previous measurements suggest. The reasons for close correspondence in previous data are not entirely clear, but it must be pointed out that very few data sets exist in which all three scalar gradient components that enter the definition of the scalar dissipation rate definition [see Eq. (4)] were measured with adequate resolution and without the use of Taylor’s hypothesis. To consider if the closeness to log-normality observed previously was caused by poor reso-

lution in measurements, we coarse-grained the data and re-plotted them. The coarse-grained data also display significant departures from log-normality. We thus conclude that the reasons for observed departures are more complex; they may also emphasize the lack of strict universality in the dissipation statistics.

The high spectral resolution in the present DNS allowed the evaluation of a conditional moment analysis as well. We have been able to confirm theoretical predictions that follow from nearly Gaussian fluctuations of the passive scalar field for $\theta < 3\theta_{\text{rms}}$, say.

In summary, we have quantified various properties of the scalar isosurfaces for conditions that are typical of many laboratory experiments in reacting flows. Beside the connections between statistical and geometrical properties of scalars studied here, it is interesting to shed more light on the formation of characteristic scalar structures with respect to time, and to relate them to the underlying local flow properties for different Reynolds numbers. This can be a useful way of incorporating Reynolds number effects on mixing in the Batchelor regime and is part of the future work.

ACKNOWLEDGMENTS

The computations were carried out on up to 256 IBM Power4 CPUs of the Jülich Multiprocessor (JUMP) machine at the John von Neumann-Institute for Computing of the Research Centre Jülich (Germany). The authors acknowledge their steady support, and the support by the Deutsche Forschungsgemeinschaft (J.S.) and by the U.S. National Science Foundation (J.S. and K.R.S.). J.S. thanks the Institute for Pure and Applied Mathematics at UCLA for hospitality during the Multiscale Geometric Analysis program, where parts of this work were done. The authors also thank R. W. Bilger, W. J. A. Dahm, J. Davoudi, J. A. Domaradzki, B. Eckhardt, S. B. Pope, and P. K. Yeung for useful discussions.

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